

Available plugins

fr_FR.png [...version française de cette page](#)

The available plugins are:

- [\[\[plugin-base:En_wiki|Plugin Base\]\]](#) : steps for loading T-Lidarpoint cloud
- [\[\[plugin-onf-ensam:En_wiki|Plugin ONF - ENSAM\]\]](#) : ground isolation, trees detection, estimation of diameter at 1.30 m
- [\[\[plugin-onf-isis:En_wiki|Plugin ONF - LSIS\]\]](#) (*PCL dependency*) : filtering clusters by circularity
- [\[\[plugin-generate:En_wiki|Generate Plugin\]\]](#) : data generation
- [\[\[plugin-toolkit:En_wiki|Plugin ToolKit\]\]](#) : utility plugin
- [\[\[plugin-meshlab:En_wiki|Plugin MeshLab\]\]](#) : plugin for use of MeshLab plugins as steps
- [\[\[plugin-lvox:En_wiki|Plugin LVOX\]\]](#) (*Not Open Source for Moment*) : voxelization , managing occlusions

Work in progress plugins:

- [\[\[plugin-onf-ign:En_wiki|Plugin ONF - IGN\]\]](#)
- [\[\[plugin-geometree:En_wiki|Plugin Geometree\]\]](#) Sébastien Bauwens Thesis (University of Liège - CIRAD)

[Previous \(Standard Graphical Interface\)](#)

[Back to summary](#)

[Next \(Batch mode\)](#)